

## MAT-19961 Calcul matriciel en génie

### Solutions - Devoir 12

1.

$$\begin{aligned}\hat{\mathbf{y}} &= \text{proj}_W \mathbf{y} = \left( \frac{\mathbf{y} \cdot \mathbf{u}_1}{\mathbf{u}_1 \cdot \mathbf{u}_1} \right) \mathbf{u}_1 + \left( \frac{\mathbf{y} \cdot \mathbf{u}_2}{\mathbf{u}_2 \cdot \mathbf{u}_2} \right) \mathbf{u}_2 + \left( \frac{\mathbf{y} \cdot \mathbf{u}_3}{\mathbf{u}_3 \cdot \mathbf{u}_3} \right) \mathbf{u}_3 \\ &= \left( \frac{4+3+0-1}{1+1+0+1} \right) \mathbf{u}_1 + \left( \frac{-4+9+3+6}{1+9+1+4} \right) \mathbf{u}_2 + \left( \frac{-4+0+3-1}{1+0+1+1} \right) \mathbf{u}_3 \\ &= 2\mathbf{u}_1 + \left( \frac{2}{3} \right) \mathbf{u}_2 + \left( -\frac{2}{3} \right) \mathbf{u}_3 \\ &= 2 \begin{bmatrix} 1 \\ 1 \\ 0 \\ 1 \end{bmatrix} + \left( \frac{2}{3} \right) \begin{bmatrix} -1 \\ 3 \\ 1 \\ -2 \end{bmatrix} + \left( -\frac{2}{3} \right) \begin{bmatrix} -1 \\ 0 \\ 1 \\ 1 \end{bmatrix} = \begin{bmatrix} 2 \\ 4 \\ 0 \\ 0 \end{bmatrix}\end{aligned}$$

$$\mathbf{z} = \mathbf{y} - \hat{\mathbf{y}} = \begin{bmatrix} 4 \\ 3 \\ 3 \\ -1 \end{bmatrix} - \begin{bmatrix} 2 \\ 4 \\ 0 \\ 0 \end{bmatrix} = \begin{bmatrix} 2 \\ -1 \\ 3 \\ -1 \end{bmatrix}$$

2. Soit  $W = [\mathbf{v}_1 \ \mathbf{v}_2]$ . La meilleure approximation de  $\mathbf{z}$  dans  $W$  est  $\text{proj}_W \mathbf{z}$ .

$$\begin{aligned}\text{proj}_W \mathbf{z} &= \left( \frac{\mathbf{z} \cdot \mathbf{v}_1}{\mathbf{v}_1 \cdot \mathbf{v}_1} \right) \mathbf{v}_1 + \left( \frac{\mathbf{z} \cdot \mathbf{v}_2}{\mathbf{v}_2 \cdot \mathbf{v}_2} \right) \mathbf{v}_2 \\ &= \left( \frac{6+7-6+3}{4+1+9+1} \right) \mathbf{v}_1 + \left( \frac{3-7+2-3}{1+1+0+1} \right) \mathbf{v}_2 \\ &= \left( \frac{2}{3} \right) \mathbf{v}_1 + \left( -\frac{5}{3} \right) \mathbf{v}_2 = \left( \frac{2}{3} \right) \begin{bmatrix} 2 \\ -1 \\ -3 \\ 1 \end{bmatrix} + \left( -\frac{5}{3} \right) \begin{bmatrix} 1 \\ 1 \\ 0 \\ -1 \end{bmatrix} = \begin{bmatrix} -1 \\ -3 \\ -2 \\ 3 \end{bmatrix}\end{aligned}$$

3. a)

$$U^T U = \begin{bmatrix} \frac{2}{3} & \frac{1}{3} & \frac{2}{3} \\ -\frac{2}{3} & \frac{2}{3} & \frac{1}{3} \\ \frac{2}{3} & \frac{1}{3} & \frac{1}{3} \end{bmatrix} \begin{bmatrix} \frac{2}{3} & -\frac{2}{3} \\ \frac{1}{3} & \frac{2}{3} \\ \frac{2}{3} & \frac{1}{3} \end{bmatrix} = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$$

$$U U^T = \begin{bmatrix} \frac{2}{3} & -\frac{2}{3} \\ \frac{1}{3} & \frac{2}{3} \\ \frac{2}{3} & \frac{1}{3} \end{bmatrix} \begin{bmatrix} \frac{2}{3} & \frac{1}{3} & \frac{2}{3} \\ -\frac{2}{3} & \frac{2}{3} & \frac{1}{3} \\ \frac{2}{3} & \frac{1}{3} & \frac{1}{3} \end{bmatrix} = \begin{bmatrix} \frac{8}{9} & -\frac{2}{9} & \frac{2}{9} \\ -\frac{2}{9} & \frac{5}{9} & \frac{4}{9} \\ \frac{2}{9} & \frac{4}{9} & \frac{5}{9} \end{bmatrix}$$

b)

$$\begin{aligned} \text{proj}_W \mathbf{y} &= \left( \frac{\mathbf{y} \cdot \mathbf{u}_1}{\mathbf{u}_1 \cdot \mathbf{u}_1} \right) \mathbf{u}_1 + \left( \frac{\mathbf{y} \cdot \mathbf{u}_2}{\mathbf{u}_2 \cdot \mathbf{u}_2} \right) \mathbf{u}_2 \\ &= \left( \frac{\frac{8}{3} + \frac{8}{3} + \frac{2}{3}}{\frac{4}{9} + \frac{1}{9} + \frac{4}{9}} \right) \mathbf{u}_1 + \left( \frac{-\frac{8}{3} + \frac{16}{3} + \frac{1}{3}}{\frac{4}{9} + \frac{4}{9} + \frac{1}{9}} \right) \mathbf{u}_2 \\ &= 6\mathbf{u}_1 + 3\mathbf{u}_2 = 6 \begin{bmatrix} \frac{2}{3} \\ \frac{1}{3} \\ \frac{2}{3} \end{bmatrix} + 3 \begin{bmatrix} -\frac{2}{3} \\ \frac{2}{3} \\ \frac{1}{3} \end{bmatrix} = \begin{bmatrix} 2 \\ 4 \\ 5 \end{bmatrix} \end{aligned}$$

$$U U^T \mathbf{y} = \begin{bmatrix} \frac{8}{9} & -\frac{2}{9} & \frac{2}{9} \\ -\frac{2}{9} & \frac{5}{9} & \frac{4}{9} \\ \frac{2}{9} & \frac{4}{9} & \frac{5}{9} \end{bmatrix} \begin{bmatrix} 4 \\ 8 \\ 1 \end{bmatrix} = \begin{bmatrix} 2 \\ 4 \\ 5 \end{bmatrix}$$

#### 4.

```
>>U
```

```
U =
```

```
   -0.6000   -0.3000    0.6000    0.1000
   -0.1000    0.2000    0.1000   -0.6000
    0.3000    0.6000    0.3000   -0.2000
    0.6000   -0.3000    0.6000   -0.1000
    0.2000   -0.1000    0.2000    0.3000
   -0.3000    0.6000    0.3000    0.2000
   -0.2000   -0.1000    0.2000   -0.3000
    0.1000    0.2000    0.1000    0.6000
```

```
>>y'
```

```
ans =
```

```
    1    1    1    1    1    1    1    1
```

```
>>(U*U'*y)'
```

```
ans =
```

```
Columns 1 through 7
```

```
    1.2000    0.4000    1.2000    1.2000    0.4000    1.2000    0.4000
```

```
Column 8
```

```
    0.4000
```

Il ne faut pas oublier de normaliser les colonnes de la matrice du problème 6.2.33. Comme la matrice  $U$  a des colonnes orthonormales, on peut utiliser le théorème. Le point le plus proche de  $\mathbf{y}$  dans  $\text{Col } U$  est la projection orthogonale de  $\mathbf{y}$  dans  $\text{Col } U$ .

#### 5.

$R = Q^T A$  et on vérifie en faisant  $QR = A$ .

```
>>format rat
```

```
>>A
```

```
A =
```

```
    5    9
    1    7
```

```

    -3      -5
    1       5

>>Q

Q =

    5/6      -1/6
    1/6       5/6
   -1/2       1/6
    1/6       1/2

>>format short
>>R=Q'*A

R =

    6.0000    12.0000
    0.0000     6.0000

>>Q*R-A

ans =

    1.0e-015 *

    0.8882     0
         0    0.8882
   -0.4441     0
         0     0

```

6. Il nous faut trouver  $Q$  et  $R$ .

Calcul de  $Q$ :

$$\mathbf{v}_1 = \mathbf{x}_1$$

$$\mathbf{v}_2 = \mathbf{x}_2 - \frac{\mathbf{x}_2 \cdot \mathbf{v}_1}{\mathbf{v}_1 \cdot \mathbf{v}_1} \mathbf{v}_1 = \begin{bmatrix} 2 \\ 1 \\ 4 \\ -4 \\ 2 \end{bmatrix} - \left( \frac{2-1-4-4+2}{5} \right) \begin{bmatrix} 1 \\ -1 \\ -1 \\ 1 \\ 1 \end{bmatrix} = \begin{bmatrix} 2 \\ 1 \\ 4 \\ -4 \\ 2 \end{bmatrix} + \begin{bmatrix} 1 \\ -1 \\ -1 \\ 1 \\ 1 \end{bmatrix} = \begin{bmatrix} 3 \\ 0 \\ 3 \\ -3 \\ 3 \end{bmatrix}$$

$$\begin{aligned}
\mathbf{v}_3 &= \mathbf{x}_3 - \frac{\mathbf{x}_3 \cdot \mathbf{v}_1}{\mathbf{v}_1 \cdot \mathbf{v}_1} \mathbf{v}_1 - \frac{\mathbf{x}_3 \cdot \mathbf{v}_2}{\mathbf{v}_2 \cdot \mathbf{v}_2} \mathbf{v}_2 = \begin{bmatrix} 5 \\ -4 \\ -3 \\ 7 \\ 1 \end{bmatrix} - \left( \frac{5+4+3+7+1}{5} \right) \begin{bmatrix} 1 \\ -1 \\ -1 \\ 1 \\ 1 \end{bmatrix} - \left( \frac{15+0-9-21+3}{9+0+9+9+9} \right) \begin{bmatrix} 3 \\ 0 \\ 3 \\ -3 \\ 3 \end{bmatrix} \\
&= \begin{bmatrix} 5 \\ -4 \\ -3 \\ 7 \\ 1 \end{bmatrix} - 4 \begin{bmatrix} 1 \\ -1 \\ -1 \\ 1 \\ 1 \end{bmatrix} + \left( \frac{1}{3} \right) \begin{bmatrix} 3 \\ 0 \\ 3 \\ -3 \\ 3 \end{bmatrix} = \begin{bmatrix} 2 \\ 0 \\ 2 \\ 2 \\ -2 \end{bmatrix}
\end{aligned}$$

En normalisant les vecteurs  $\mathbf{v}_1$ ,  $\mathbf{v}_2$  et  $\mathbf{v}_3$ , on obtient la matrice  $Q$ .

$$Q = \begin{bmatrix} \frac{1}{\sqrt{5}} & \frac{1}{2} & \frac{1}{2} \\ -\frac{1}{\sqrt{5}} & 0 & 0 \\ -\frac{1}{\sqrt{5}} & \frac{1}{2} & \frac{1}{2} \\ \frac{1}{\sqrt{5}} & -\frac{1}{2} & \frac{1}{2} \\ \frac{1}{\sqrt{5}} & \frac{1}{2} & -\frac{1}{2} \end{bmatrix}$$

$$R = Q^T A = \begin{bmatrix} \frac{1}{\sqrt{5}} & -\frac{1}{\sqrt{5}} & -\frac{1}{\sqrt{5}} & \frac{1}{\sqrt{5}} & \frac{1}{\sqrt{5}} \\ \frac{1}{2} & 0 & \frac{1}{2} & -\frac{1}{2} & \frac{1}{2} \\ \frac{1}{2} & 0 & \frac{1}{2} & \frac{1}{2} & -\frac{1}{2} \end{bmatrix} \begin{bmatrix} 1 & 2 & 5 \\ -1 & 1 & -4 \\ -1 & 4 & -3 \\ 1 & -4 & 7 \\ 1 & 2 & 1 \end{bmatrix} = \begin{bmatrix} \sqrt{5} & -\sqrt{5} & 4\sqrt{5} \\ 0 & 6 & -2 \\ 0 & 0 & 4 \end{bmatrix}$$

7.

A =

$$\begin{bmatrix} -10 & 13 & 7 & -11 \\ 2 & 1 & -5 & 3 \\ -6 & 3 & 13 & -3 \\ 16 & -16 & -2 & 5 \end{bmatrix}$$

```

      2      1      -5      -7
>>v1=A(:,1)/norm(A(:,1))
v1 =
    -0.5000
     0.1000
    -0.3000
     0.8000
     0.1000
>>v2=A(:,2)-(v1*v1')*A(:,2)
v2 =
     3.0000
     3.0000
    -3.0000
     0.0000
     3.0000
>>v2=v2/norm(v2)
v2 =
     0.5000
     0.5000
    -0.5000
     0.0000
     0.5000
>>Q=[v1 v2];
>>v3=A(:,3)-(Q*Q')*A(:,3)
v3 =
     6.0000
     0.0000
     6.0000
     6.0000
     0.0000
>>v3=v3/norm(v3)
v3 =

```

```

0.5774
0.0000
0.5774
0.5774
0.0000

>>Q=[Q v3];
>>v4=A(:,4)-(Q*Q')*A(:,4)

v4 =

-0.0000
5.0000
0
0.0000
-5.0000

>>v4=v4/norm(v4)

v4 =

-0.0000
0.7071
0
0.0000
-0.7071

>>Q=[Q v4]

Q =

-0.5000    0.5000    0.5774   -0.0000
 0.1000    0.5000    0.0000    0.7071
-0.3000   -0.5000    0.5774         0
 0.8000    0.0000    0.5774    0.0000
 0.1000    0.5000    0.0000   -0.7071

>>R=Q'*A

R =

20.0000  -20.0000  -10.0000   10.0000
 0.0000    6.0000   -8.0000   -6.0000
 0.0000   -0.0000  10.3923   -5.1962
 0.0000   -0.0000   -0.0000    7.0711

```

```
>>A-Q*R
```

```
ans =
```

```
1.0e-013 *
```

```
-0.0888    0.0888    0.0444   -0.0178  
-0.1243    0.1266    0.0266   -0.0488  
         0   -0.0044    0.0355   -0.0089  
-0.0355         0    0.0444         0  
 0.0377   -0.0466   -0.0444    0.0355
```